

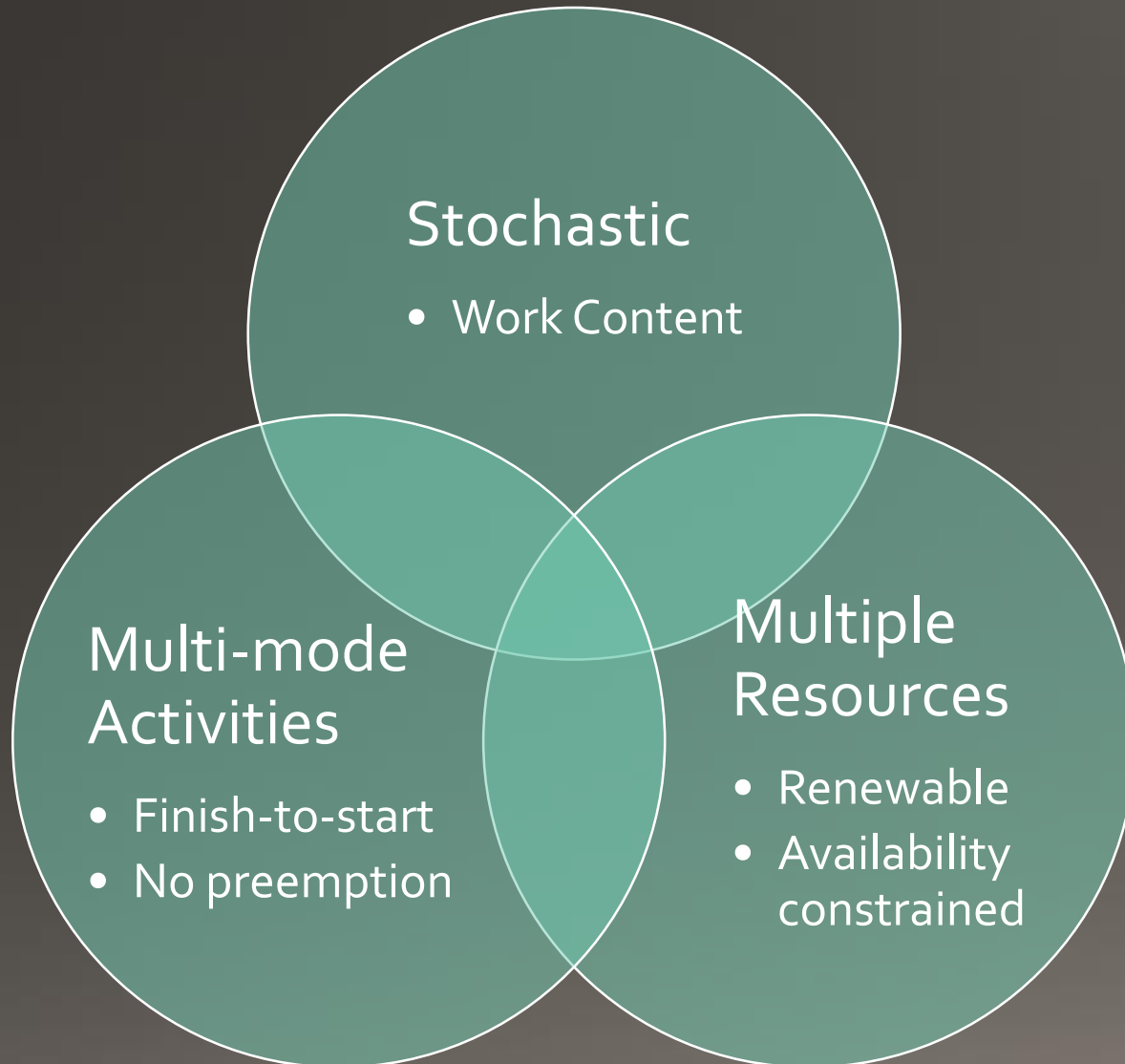
Scheduling of Multimodal Activities with Multiple Renewable and Availability Constrained Resources under Stochastic Conditions

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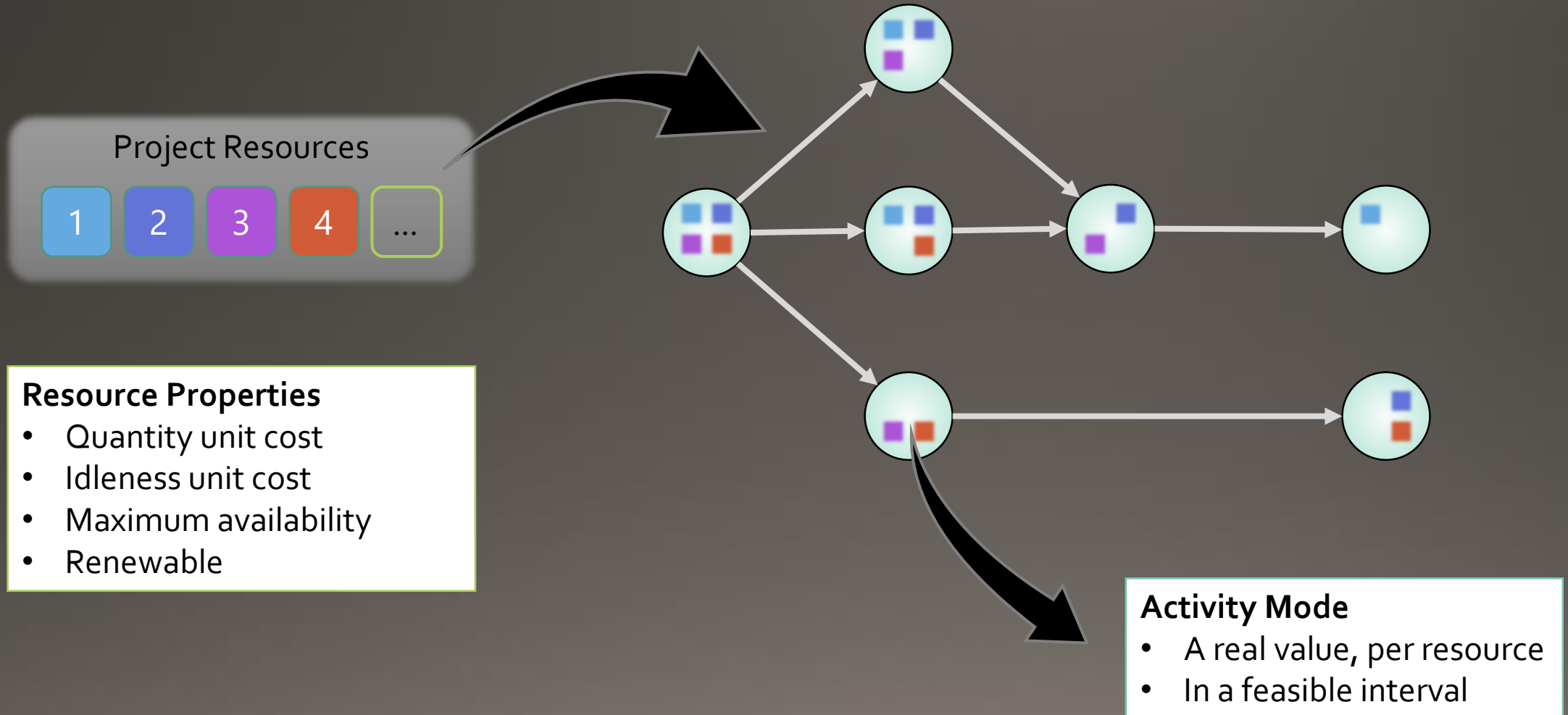


The Model – Overview





The Model – Multiple Resources

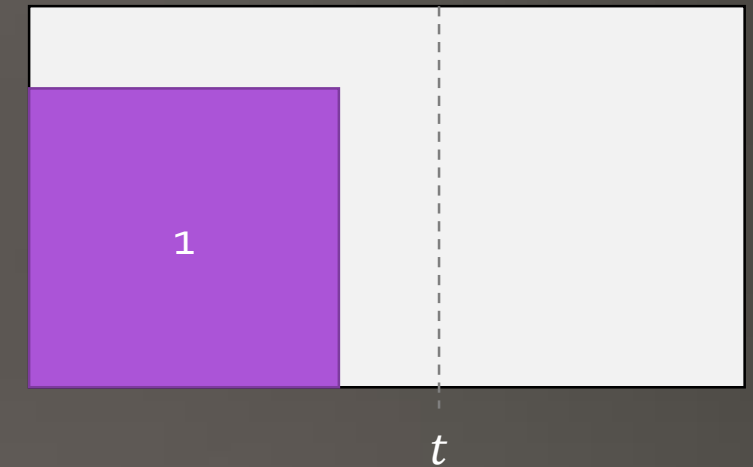
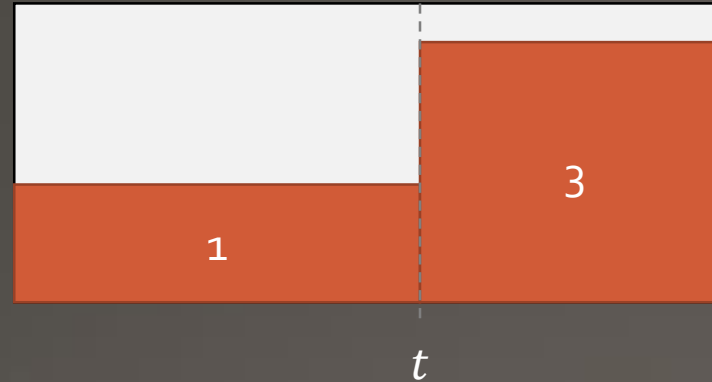
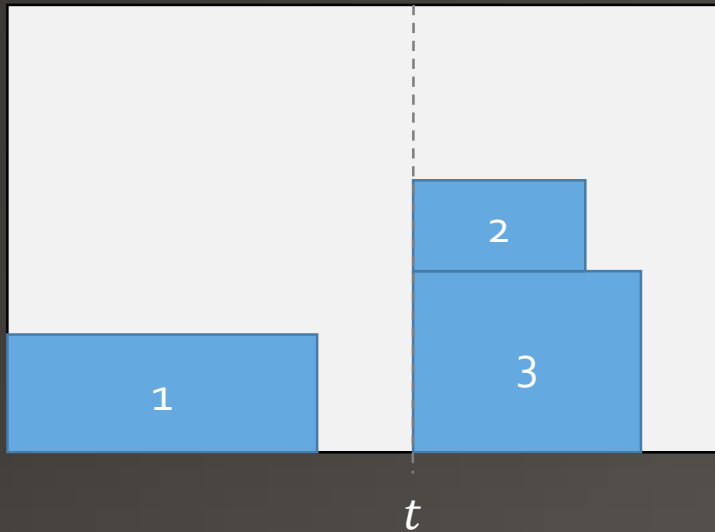




The Model – Schedule

$N = 3$ Precedence: (1,2)

$1 \rightarrow \{\text{blue}, \text{orange}, \text{purple}\}$ $2 \rightarrow \{\text{blue}\}$ $3 \rightarrow \{\text{blue}, \text{orange}\}$



Delay due to Precedence

- Activity 2 postponed to t (after activity 1)

Delay due to Resource Capacity

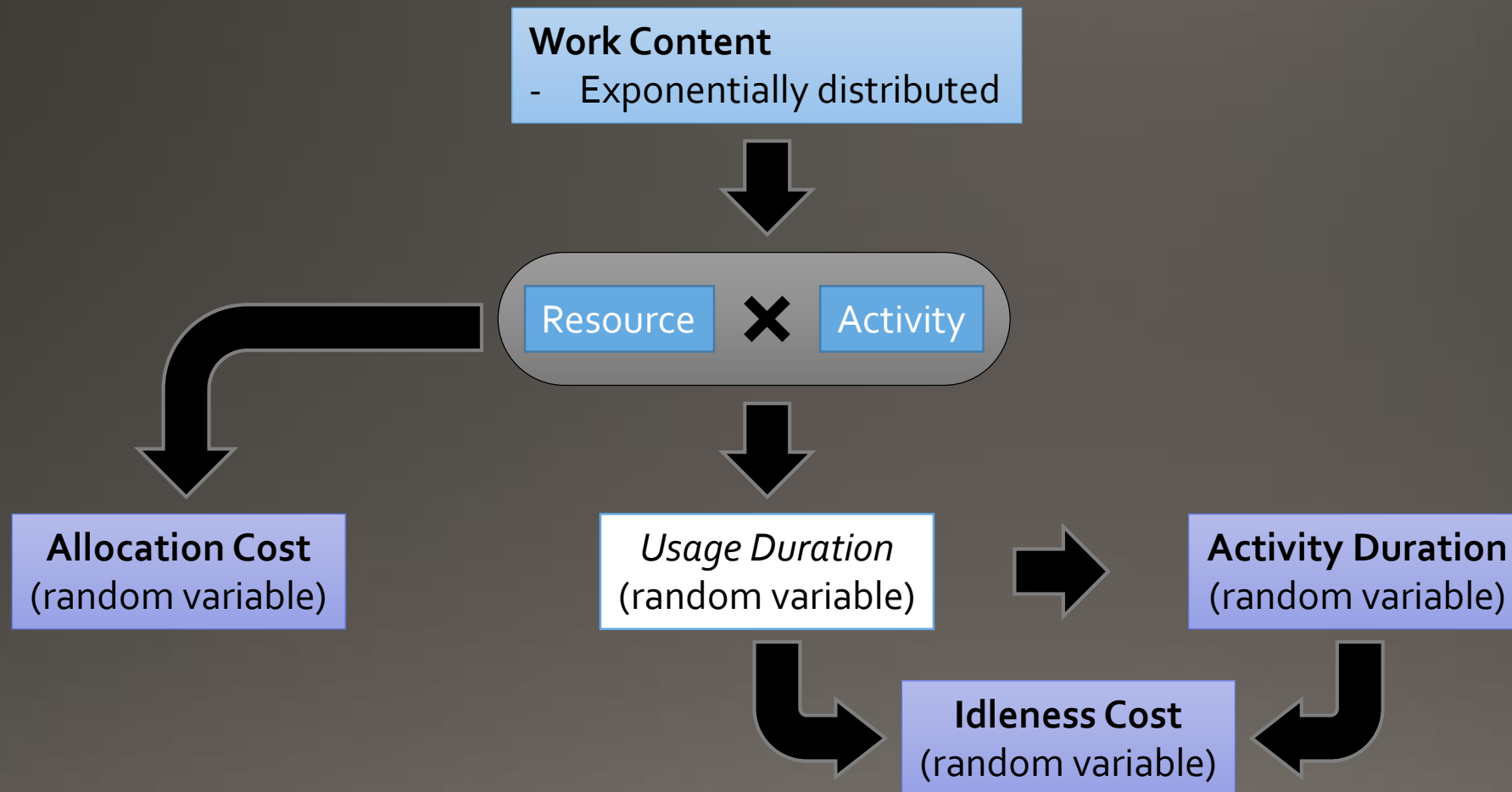
- Activity 3 “forced” to start only at t because 1 claimed too much orange resource

No Resource Balance

- The complete availability usage is not enforced



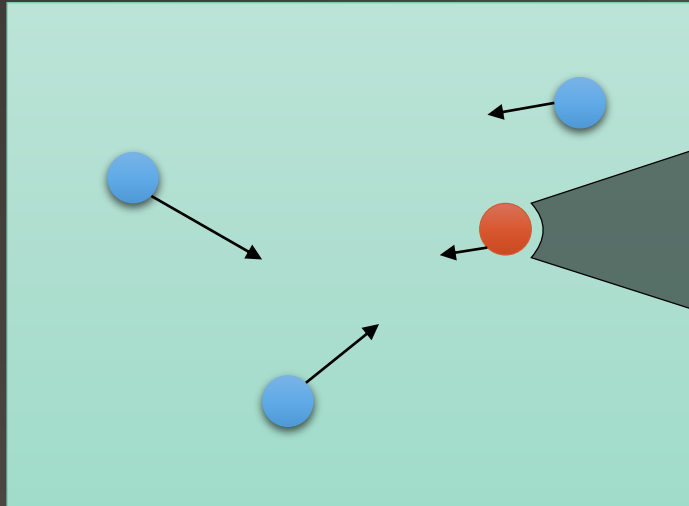
The Model – Stochastic Nature





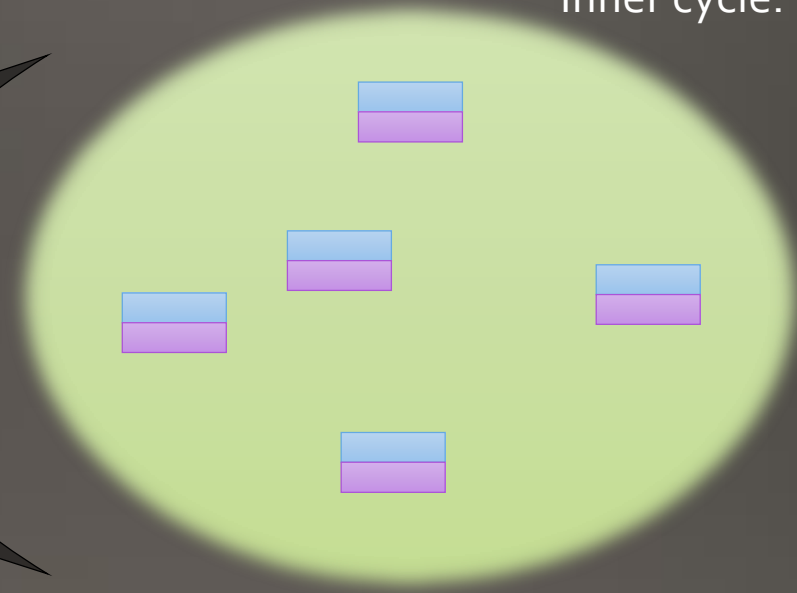
Implementation – Overview

Outer cycle: Electromagnetic method



Particles moving (candidate solution)
Coordinates → allocation table
Greater attraction → better cost

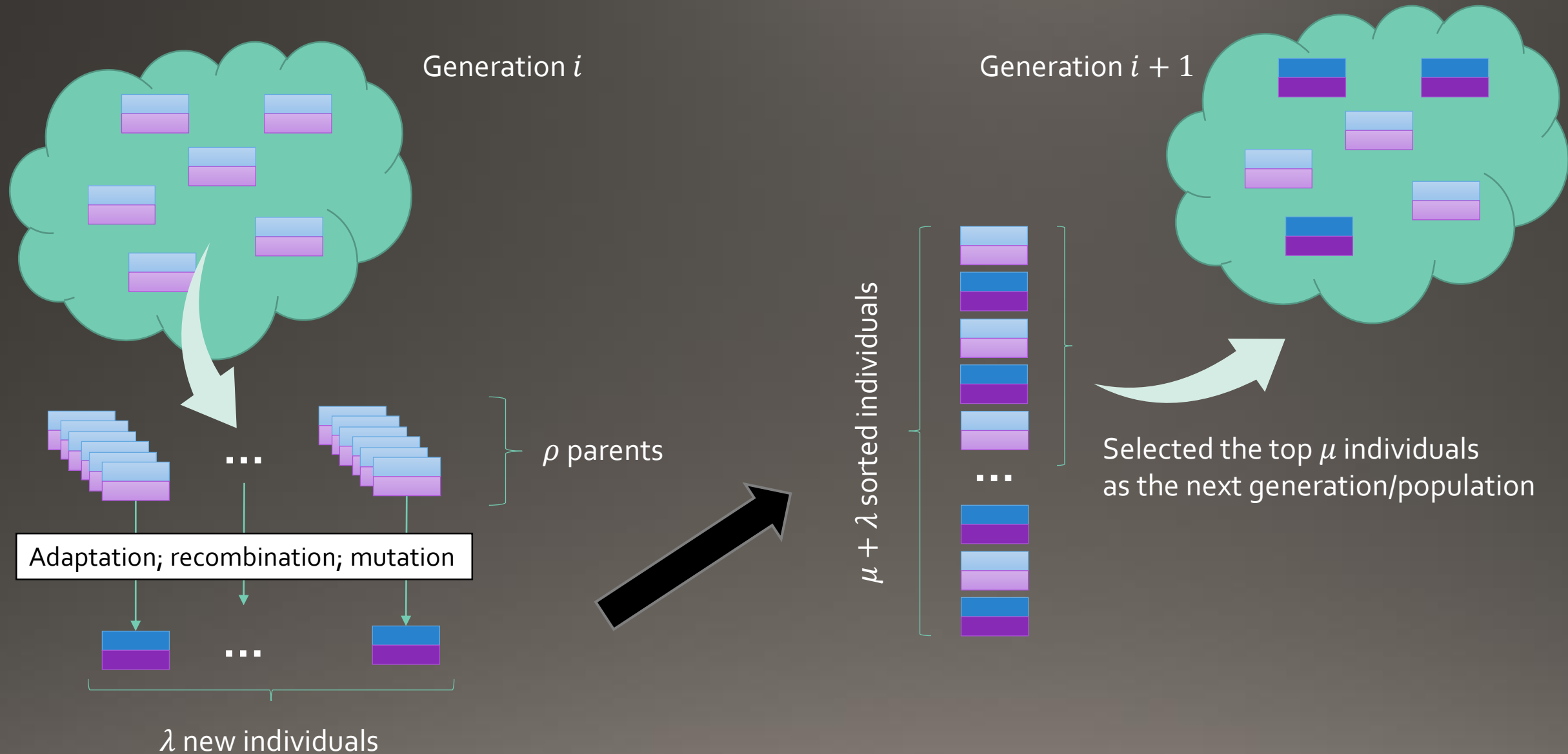
Inner cycle: ES ($\mu/\rho + \lambda$)



Population changing between generations
Coordinates (data ■) → activity ordering
Coordinates (sd ■) → stepping control
Better schedule → best fit (in population)

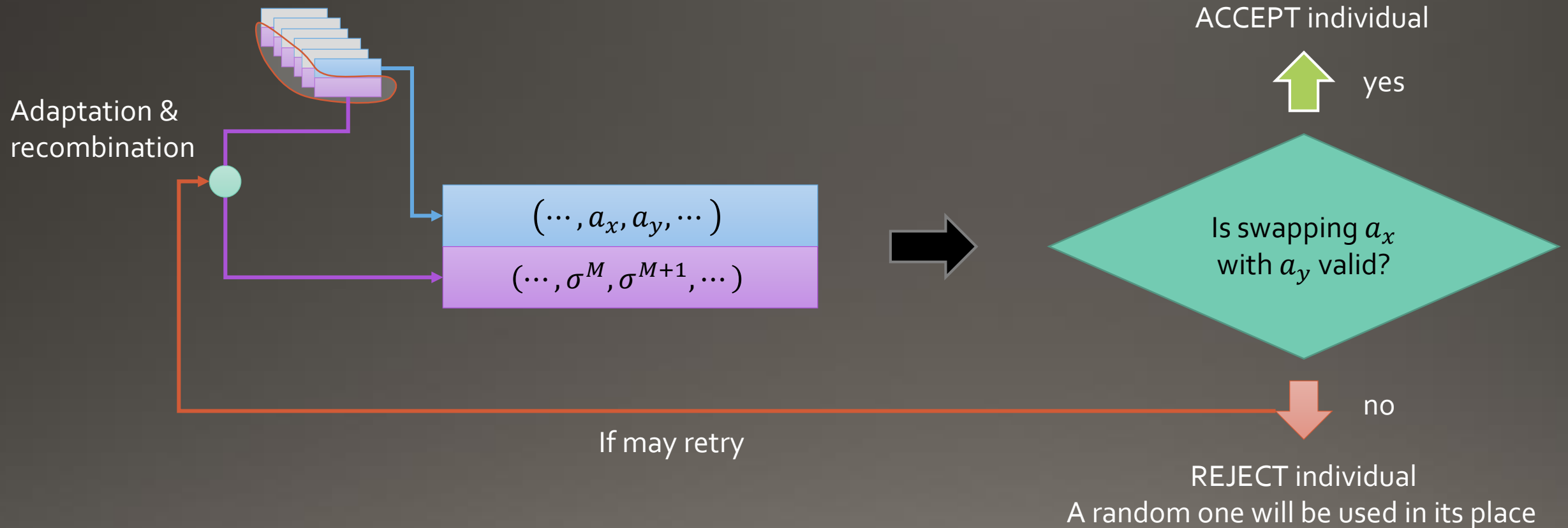


Implementation – ES ($\mu/\rho + \lambda$)





Implementation – Validation





Discussion – Test Cases

Test Case A

$$N = 11 \quad T_D = 28$$

$$c_L = 8 \quad c_E = 0.8$$

single resource

$$R_1 = 1.5$$



A-S

multiple resources

$$R_1 = 3 \quad R_2 = 3 \quad R_3 = 3$$



A-M

Test Case B

$$N = 24 \quad T_D = 223$$

$$c_L = 12 \quad c_E = 1.2$$

single resource

$$R_1 = 5$$



B-S

multiple resources

$$R_1 = 1.5 \quad R_2 = 3$$

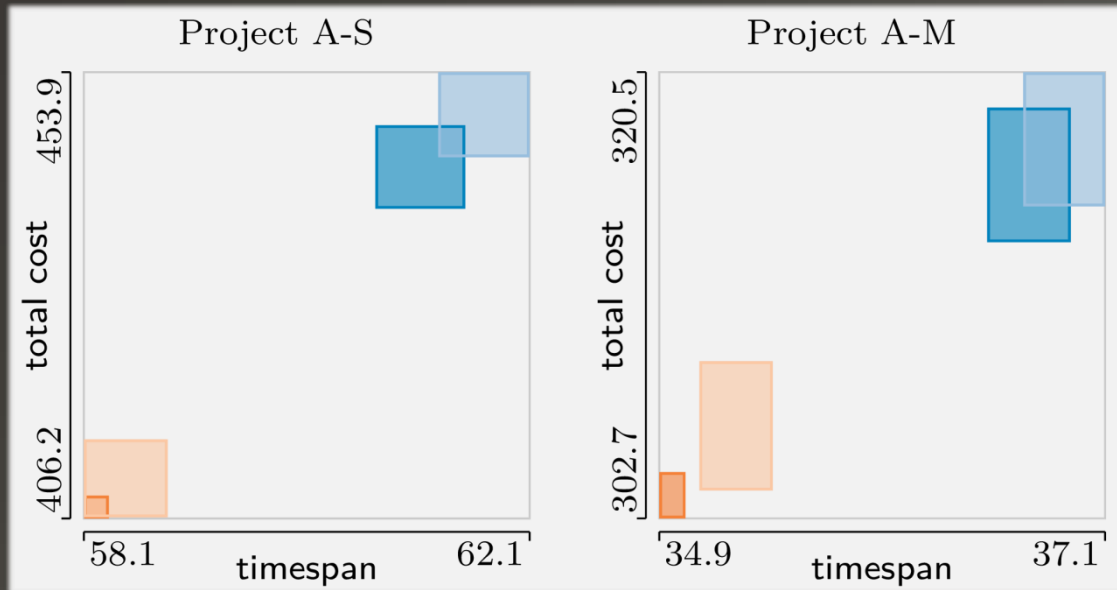


B-M

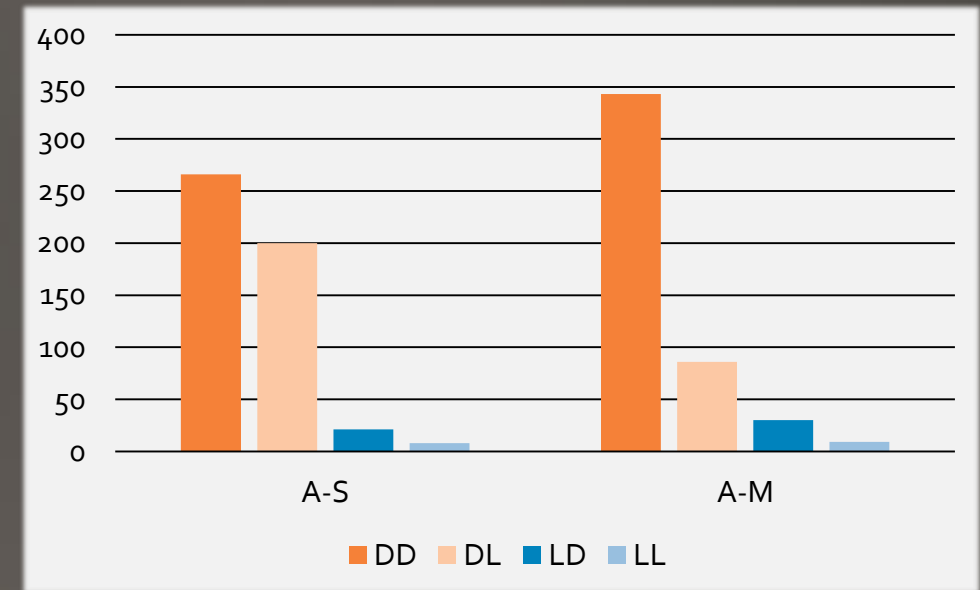


Discussion – Configurations (A)

Confidence Intervals for the Mean at 90%



Mean Execution Time per Simulation (ms)



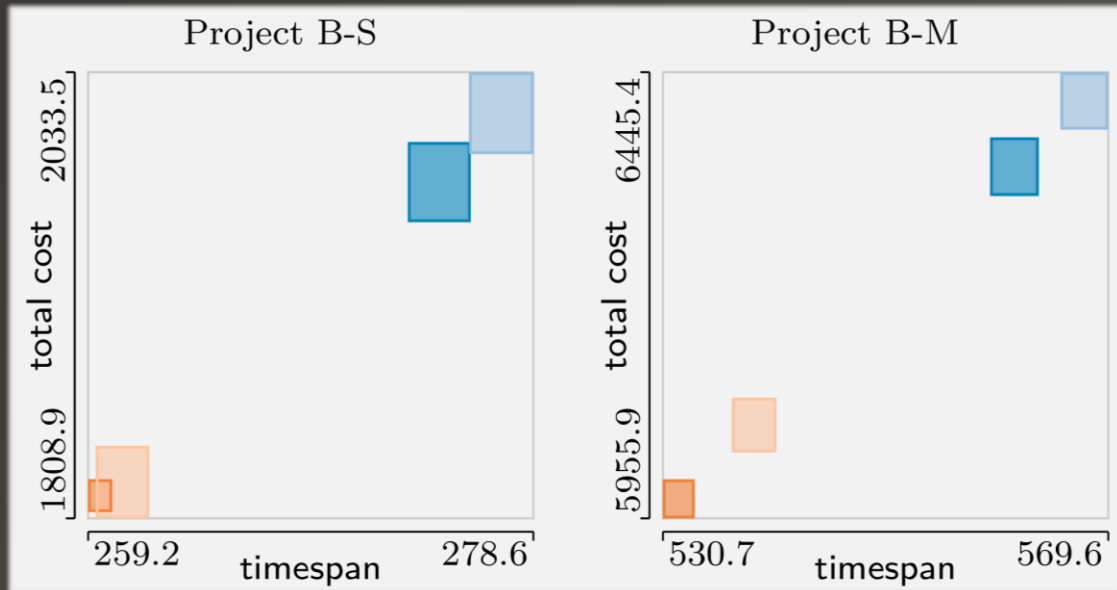
- DD & DL achieve both lesser cost and lesser timespan
- DD marginally better at timespan than DL, in A-M

- DD & DL take much longer than LD & LL

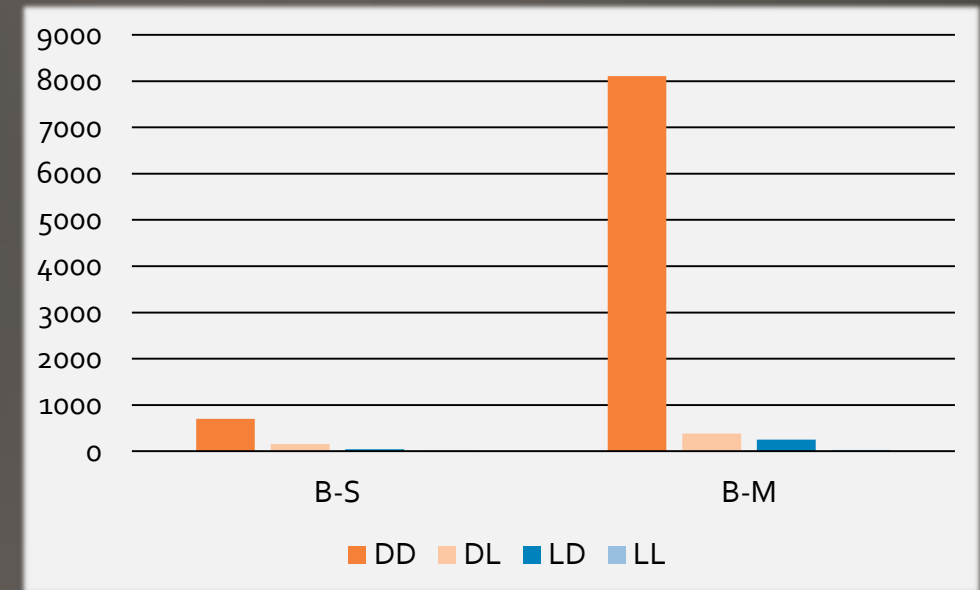


Discussion – Configurations (B)

Confidence Intervals for the Mean at 90%



Mean Execution Time per Simulation (ms)



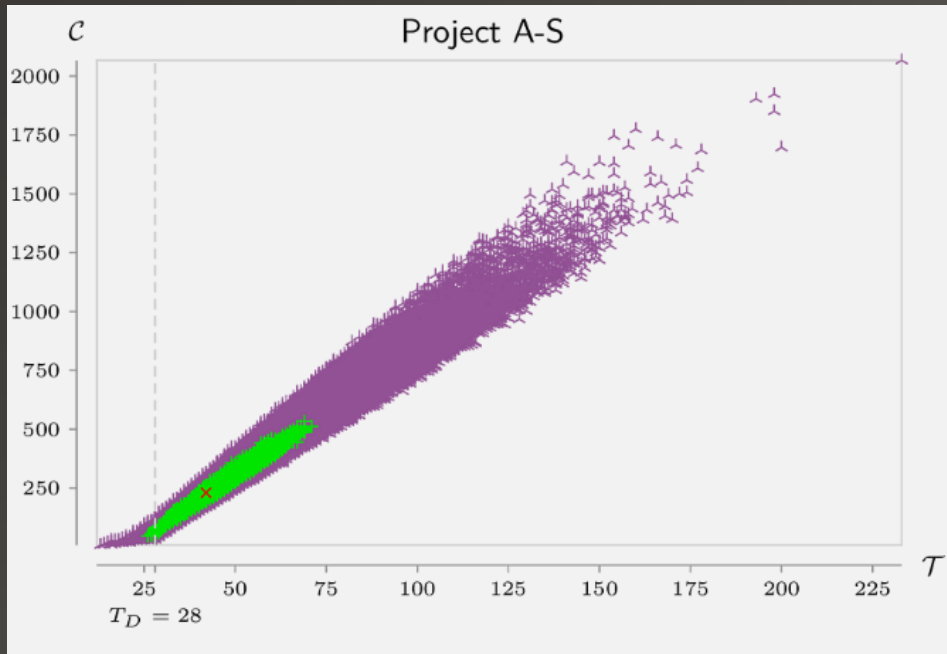
- DD & DL achieve both lesser cost and lesser timespan
- DD better at both cost and timespan than DL, in B-M

- DD & DL take much longer than LD & LL
- DD at B-M is abnormally greater

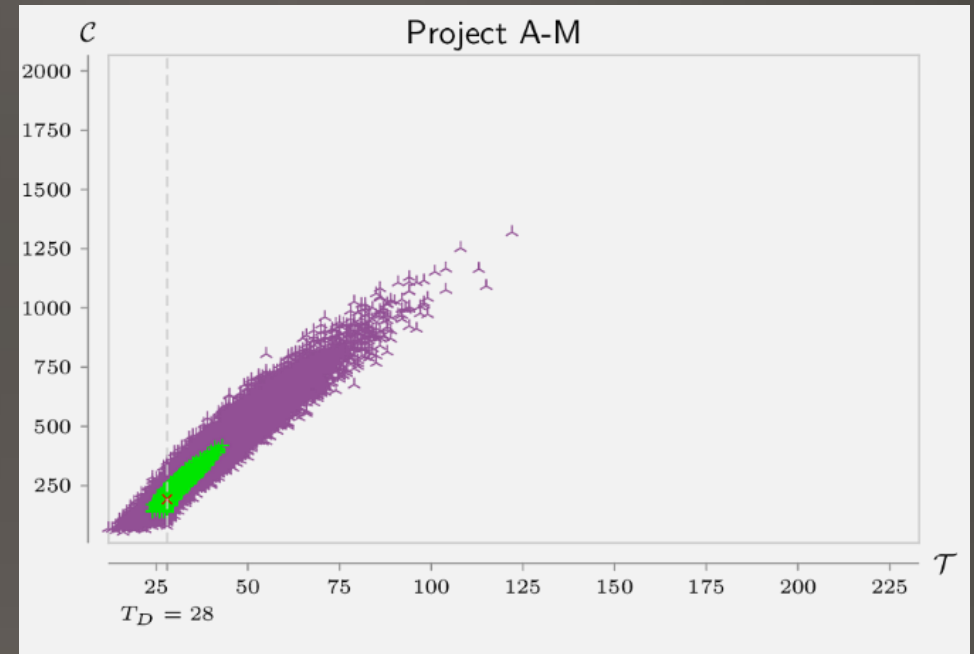


Discussion – Dispersion ($A@DD$)

Scatter Plots: Overall Distribution of the Obtained Results



- Different behavior before and after T_D : bonus versus penalty
- More frequent results around T_D

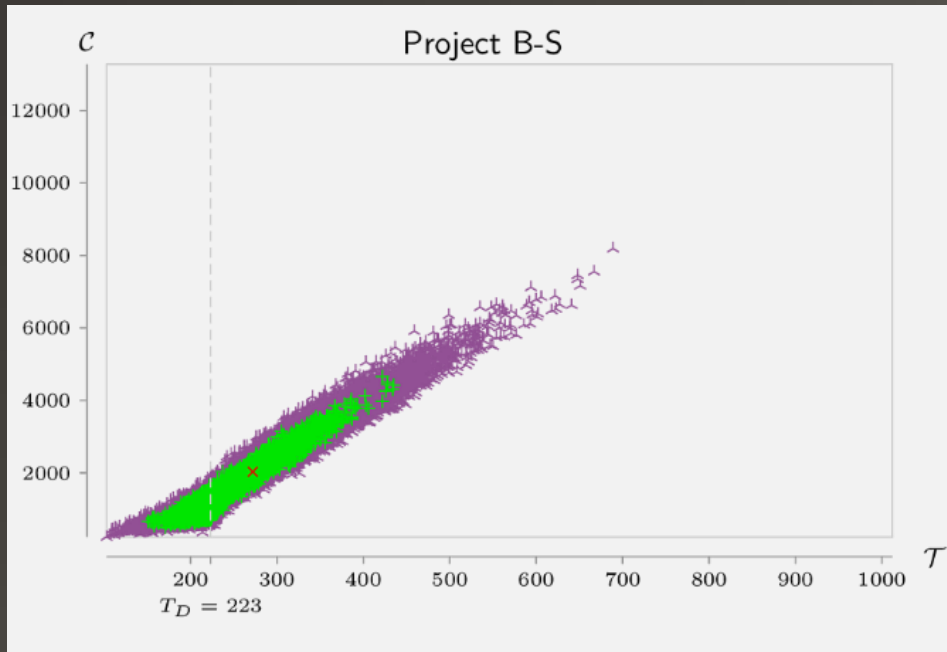


- A-M with lesser timespan and cost: maximum availability is more permissive
- The cost amplitude, per each timespan value, is greater for A-M

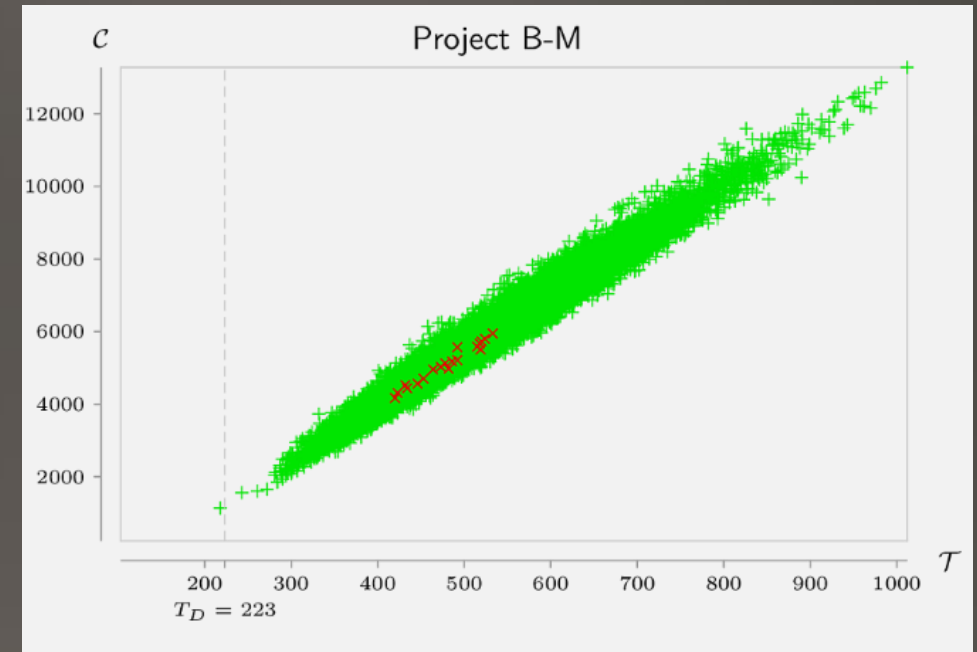


Discussion – Dispersion ($B@DD$)

Scatter Plots: Overall Distribution of the Obtained Results



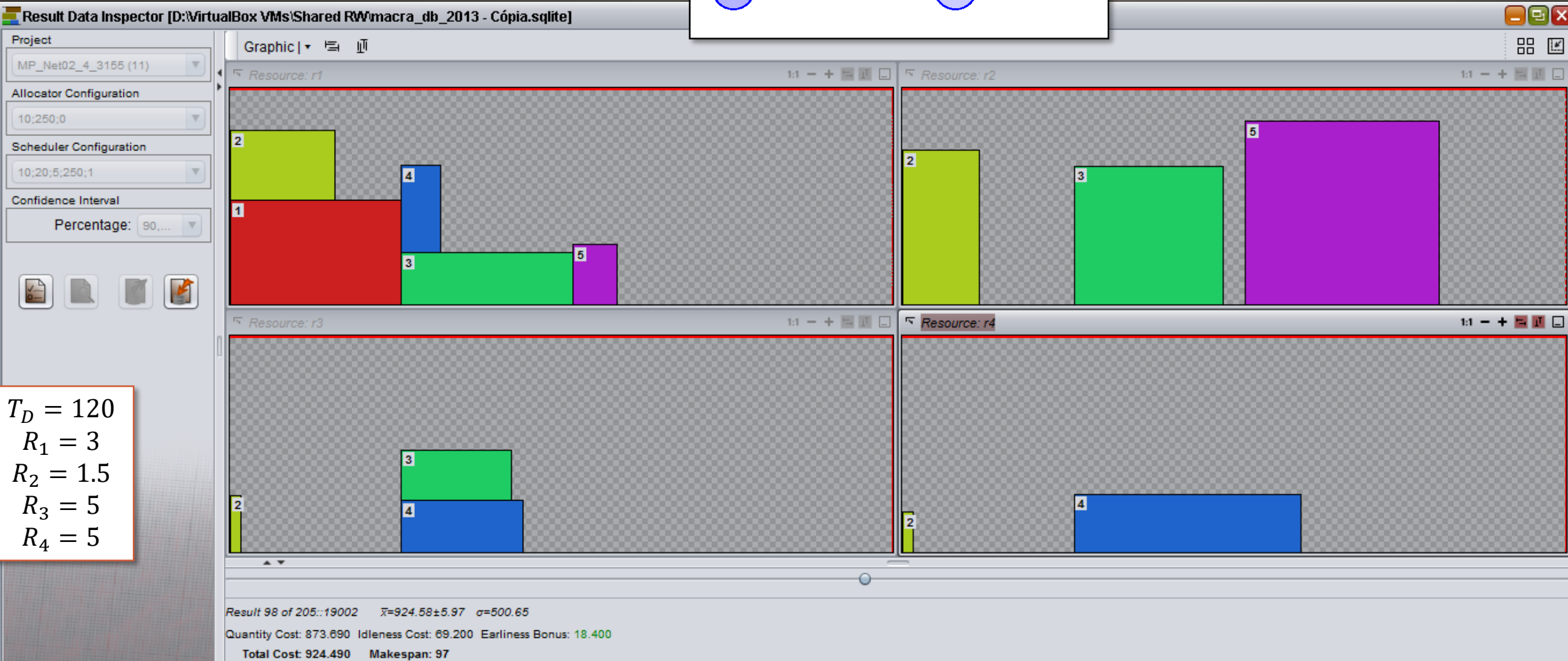
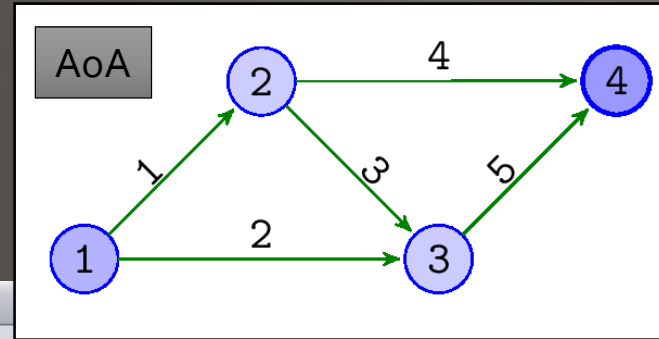
- B-S within A-S (and A-M) observations



- B-M results (almost) all above T_D .
- B-M not showing apparent convergence (multiple modal results)



Example



$$T_D = 120$$

$$R_1 = 3$$

$$R_2 = 1.5$$

$$R_3 = 5$$

$$R_4 = 5$$



Conclusions

Sensibility

- EM algorithm configuration
- Maximum resource availability

Multiple Resources

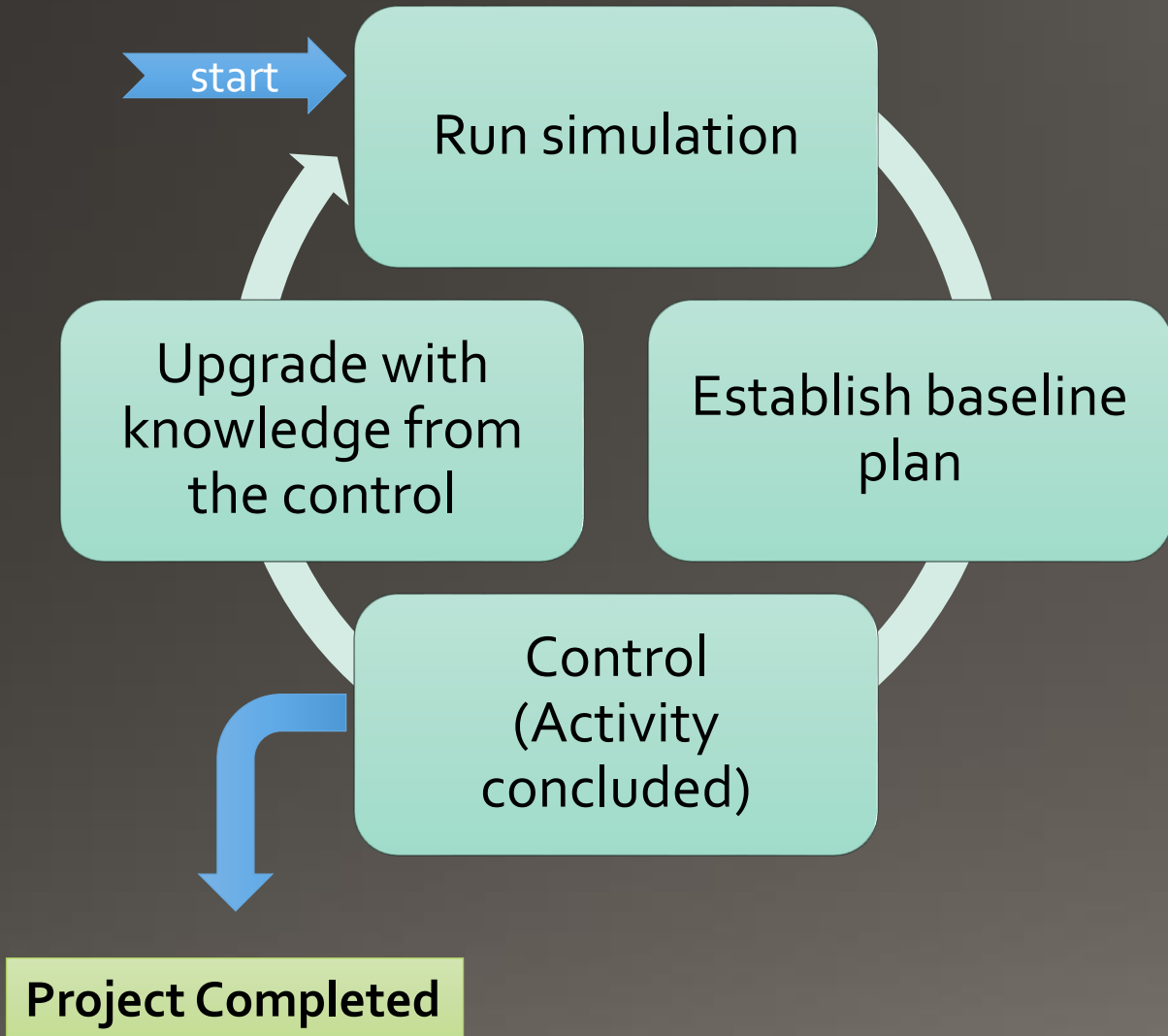
- Wider cost interval for each project duration (idleness cost)

Convergence

- Project duration tends towards due date
- Scarce results with both great cost and time
- Due date if overoptimistic may disrupt convergence



Future Research



Immediate caveats

- What to do if many activities finish at the same time (control)?
- The simulation rerunning must be kept swift



Your Questions!