

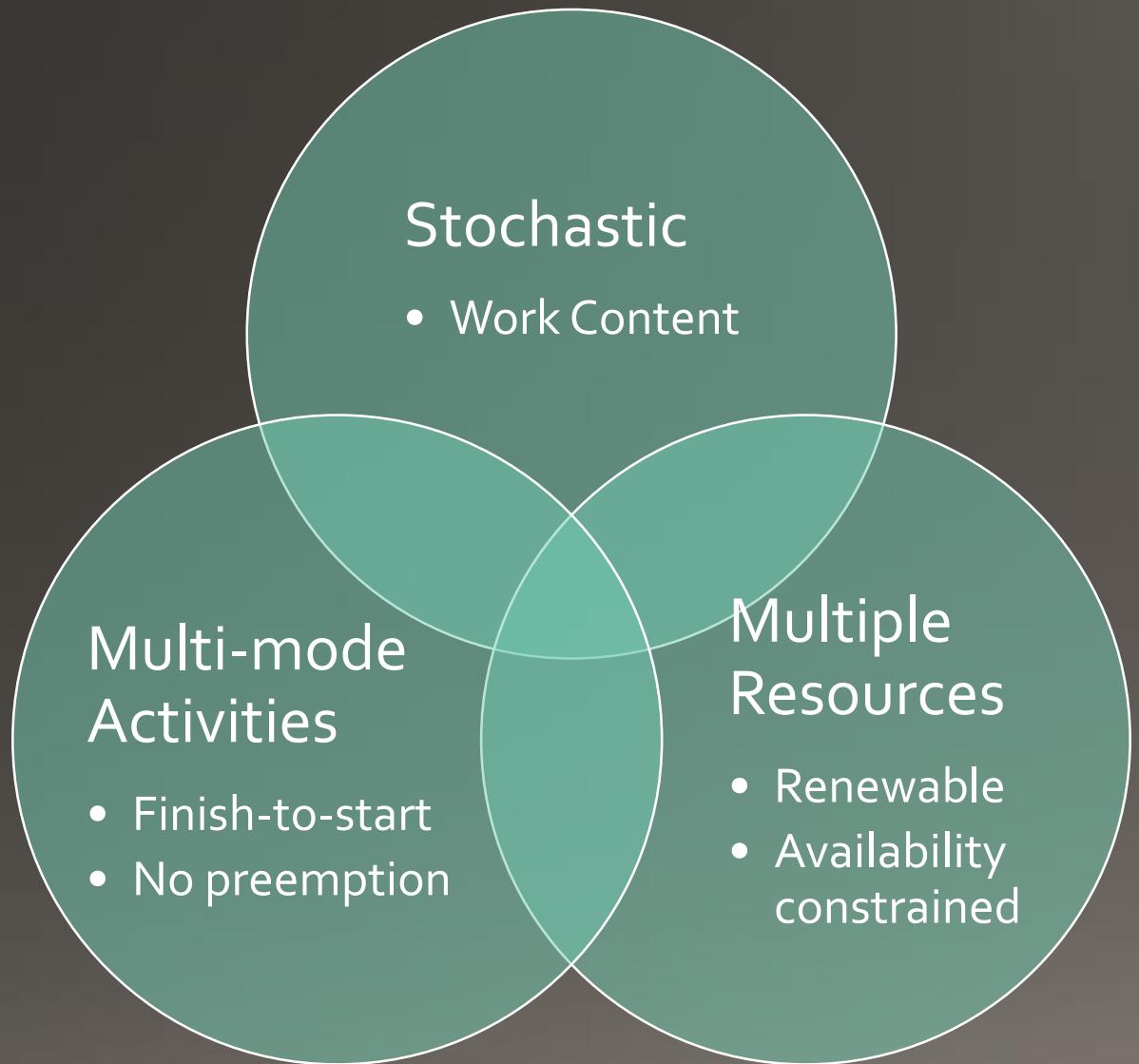


Scheduling of Multimodal Activities with Multiple Renewable and Availability Constrained Resources under Stochastic Conditions

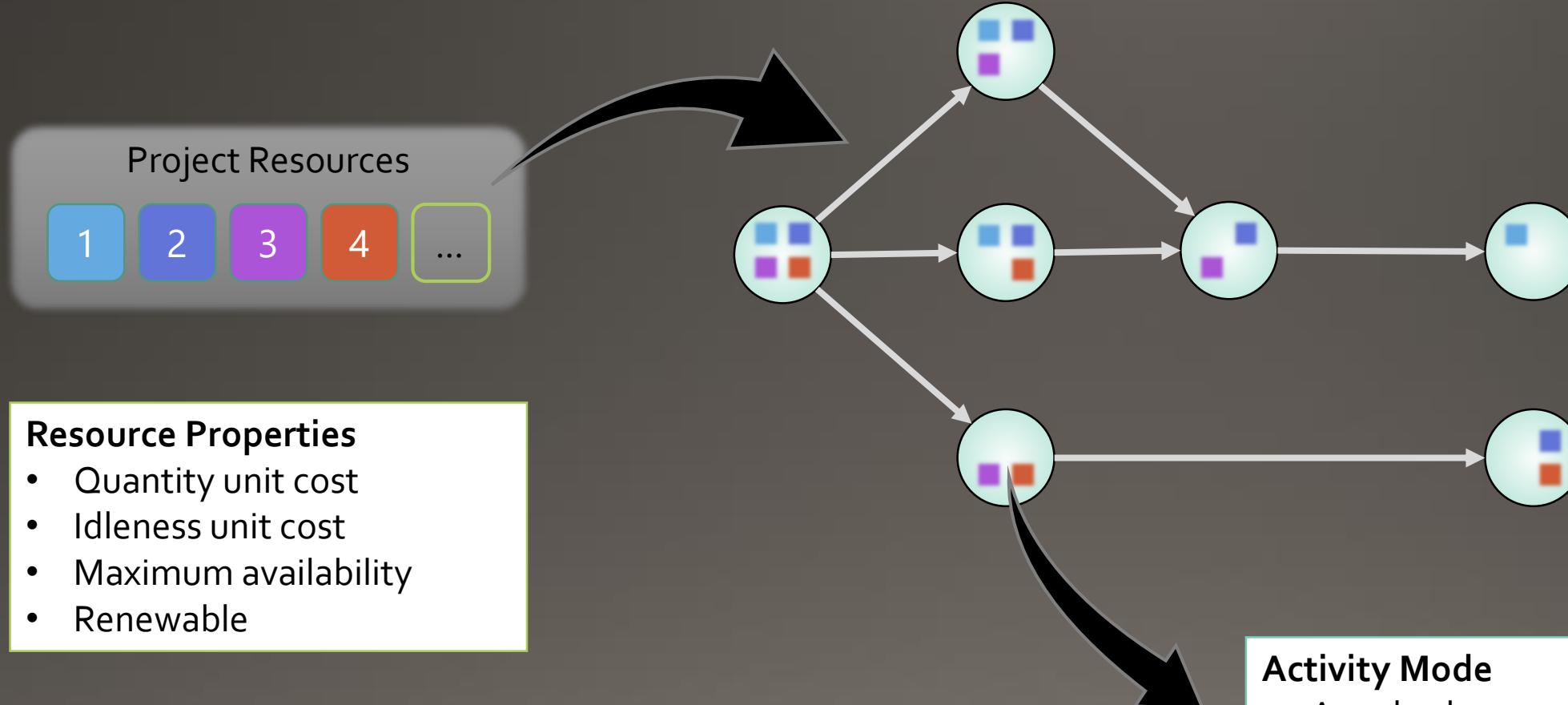
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The Model – Overview



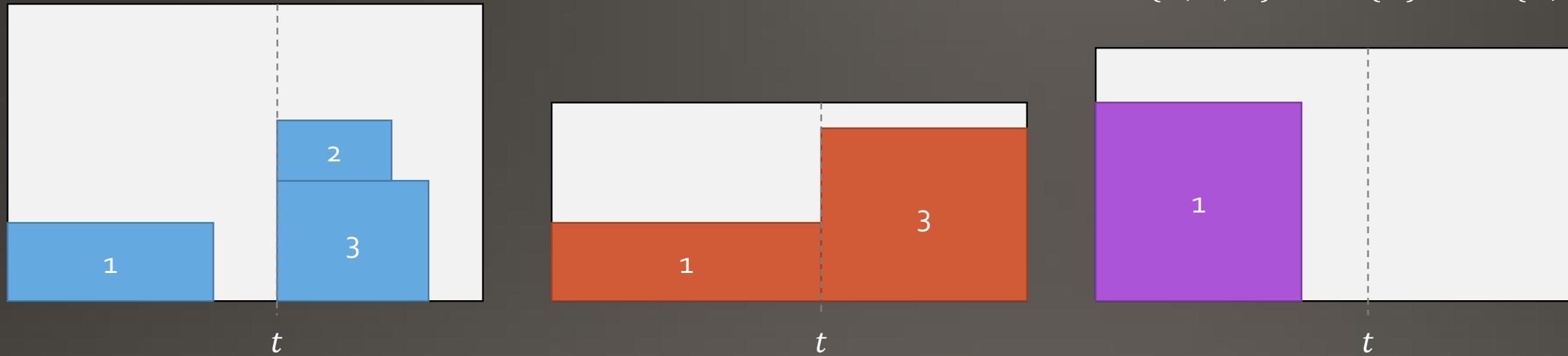
The Model – Multiple Resources



The Model – Schedule

$N = 3$ Precedence: (1,2)

$1 \rightarrow \{\square, \blacksquare, \blacksquare\}$ $2 \rightarrow \{\square\}$ $3 \rightarrow \{\square, \blacksquare\}$



Delay due to Precedence

- Activity 2 postponed to t (after activity 1)

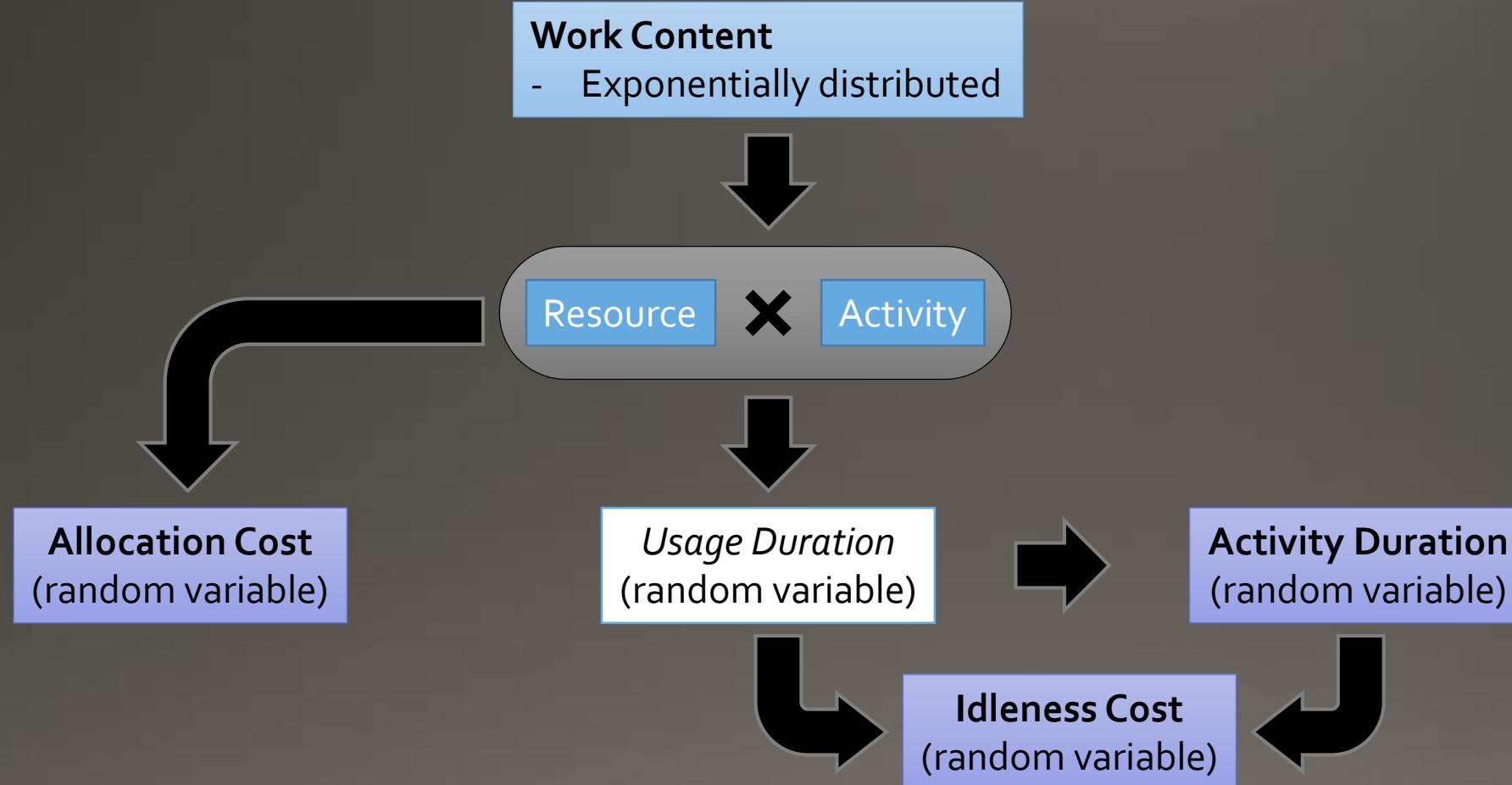
No Resource Balance

- The complete availability usage is not enforced

Delay due to Resource Capacity

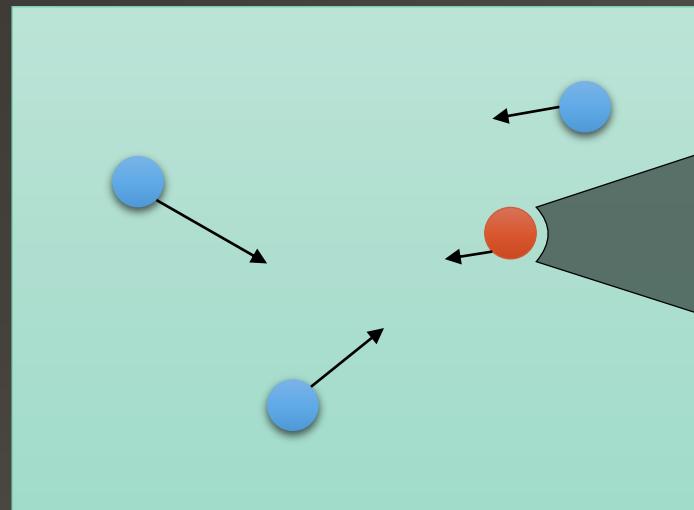
- Activity 3 “forced” to start only at t because 1 claimed too much orange resource

The Model – Stochastic Nature



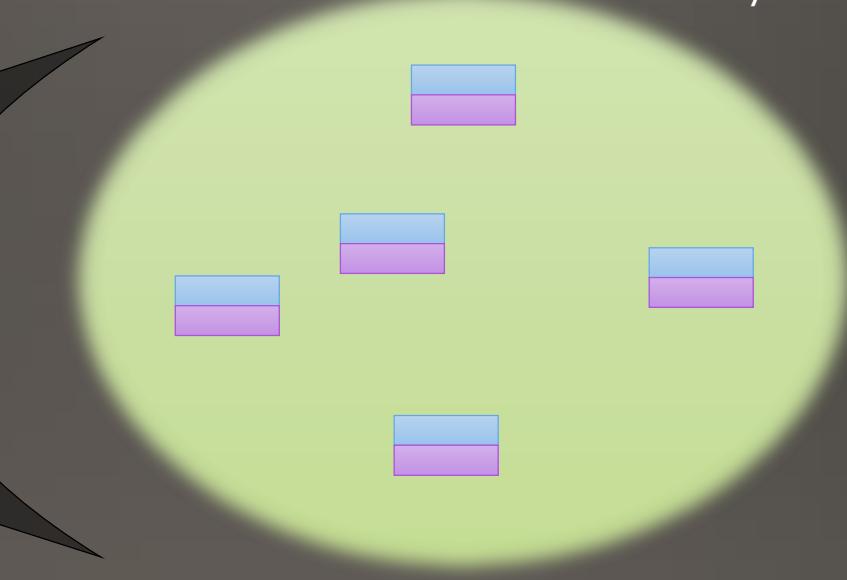
Implementation – Overview

Outer cycle: Electromagnetic method



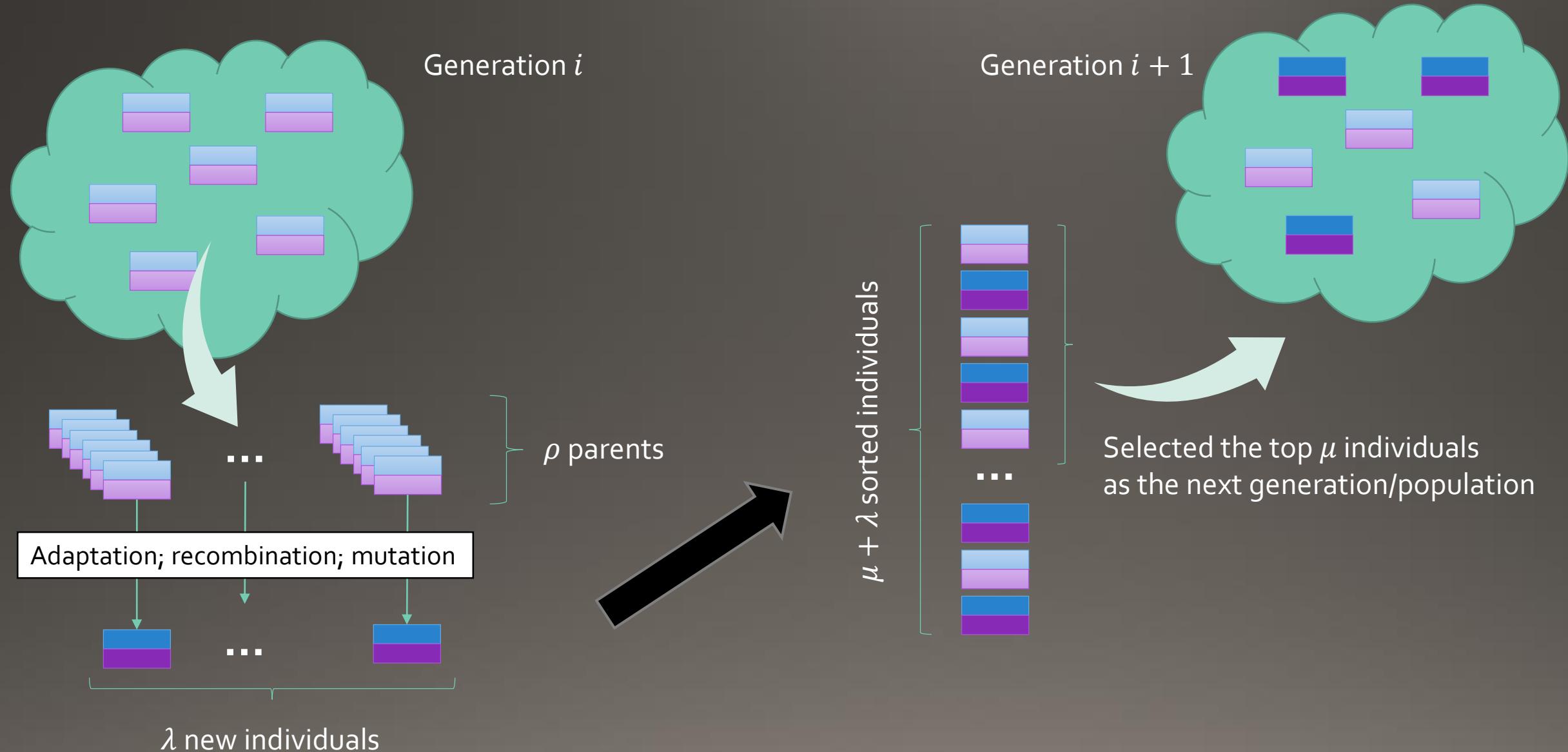
Particles moving (candidate solution)
Coordinates → allocation table
Greater attraction → better cost

Inner cycle: ES ($\mu/\rho + \lambda$)

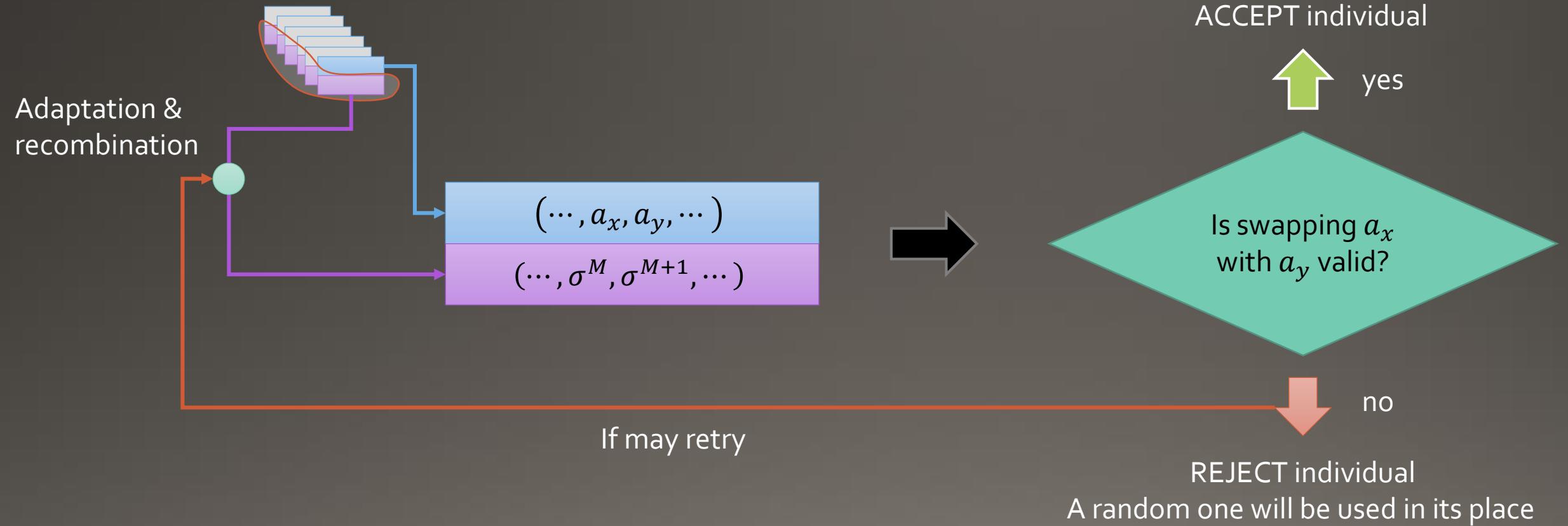


Population changing between generations
Coordinates (data ■) → activity ordering
Coordinates (sd ■) → stepping control
Better schedule → best fit (in population)

Implementation – ES ($\mu/\rho + \lambda$)



Implementation – Validation



Discussion – Test Cases

Test Case A

$N = 11$ $T_D = 28$

$c_L = 8$ $c_E = 0.8$

single resource

multiple resources

$R_1 = 1.5$

$R_1 = 3$ $R_2 = 3$ $R_3 = 3$



A-S



A-M

Test Case B

$N = 24$ $T_D = 223$

$c_L = 12$ $c_E = 1.2$

single resource

multiple resources

$R_1 = 5$

$R_1 = 1.5$ $R_2 = 3$



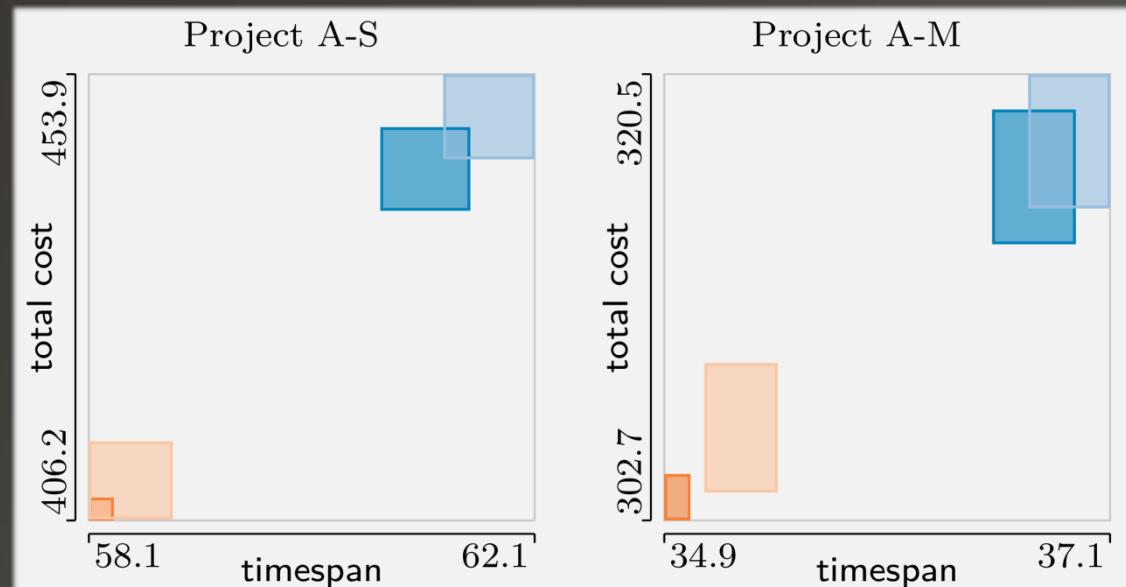
B-S



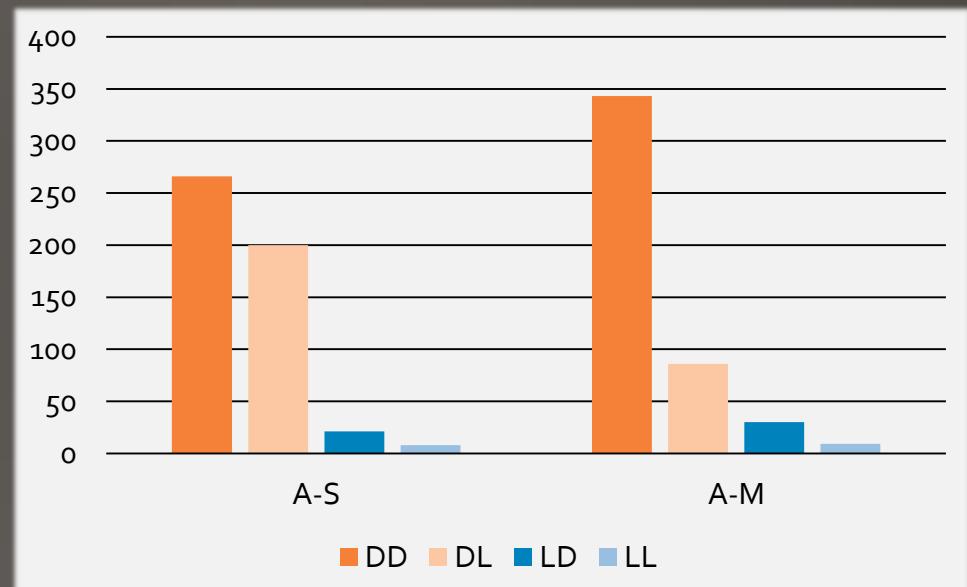
B-M

Discussion – Configurations (A)

Confidence Intervals for the Mean at 90%



Mean Execution Time per Simulation (ms)

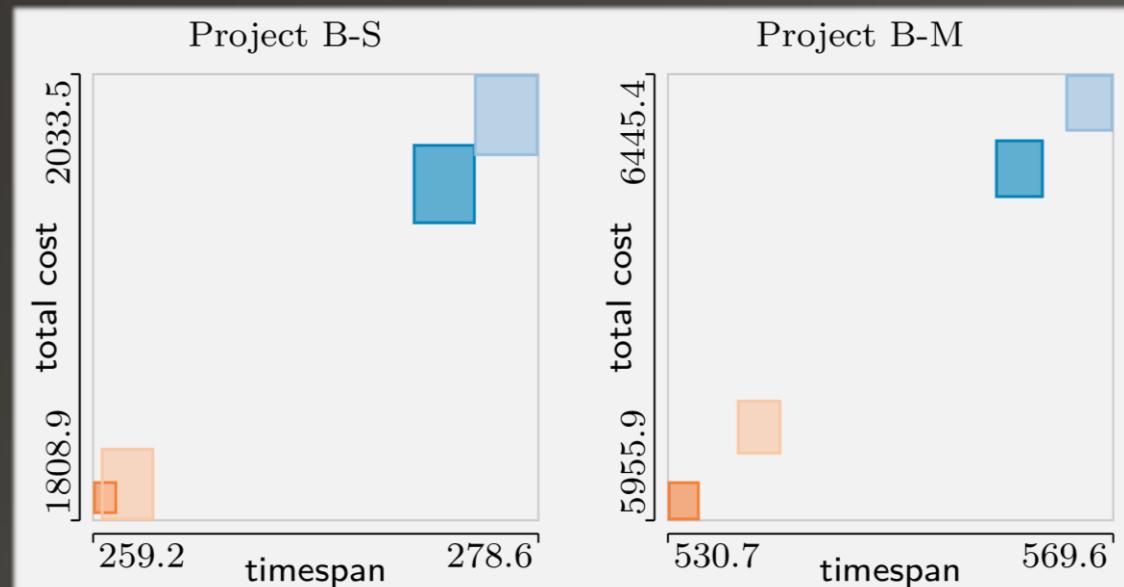


- DD & DL achieve both lesser cost and lesser timespan
- DD marginally better at timespan than DL, in A-M

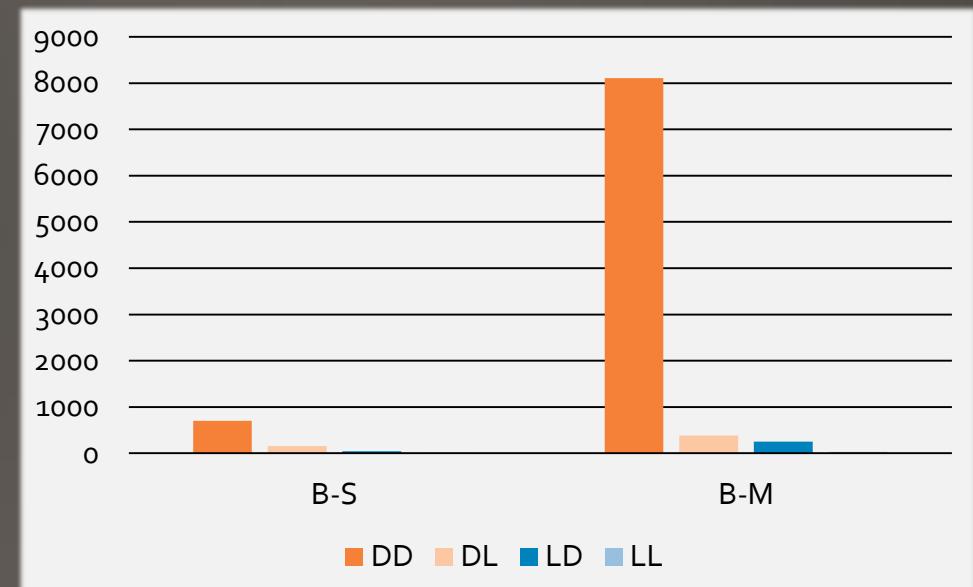
- DD & DL take much longer than LD & LL

Discussion – Configurations (B)

Confidence Intervals for the Mean at 90%



Mean Execution Time per Simulation (ms)

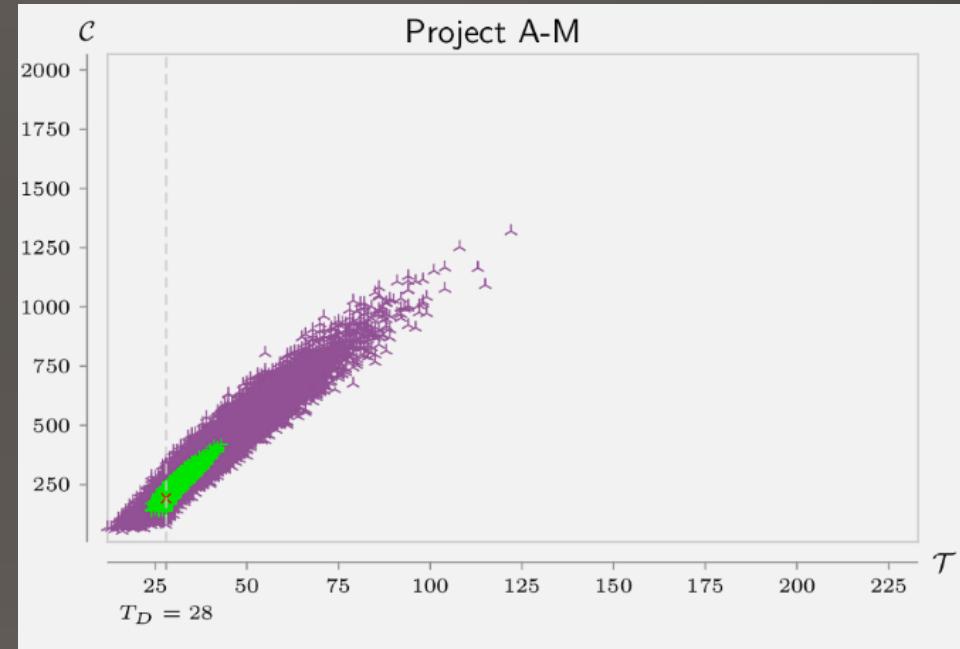
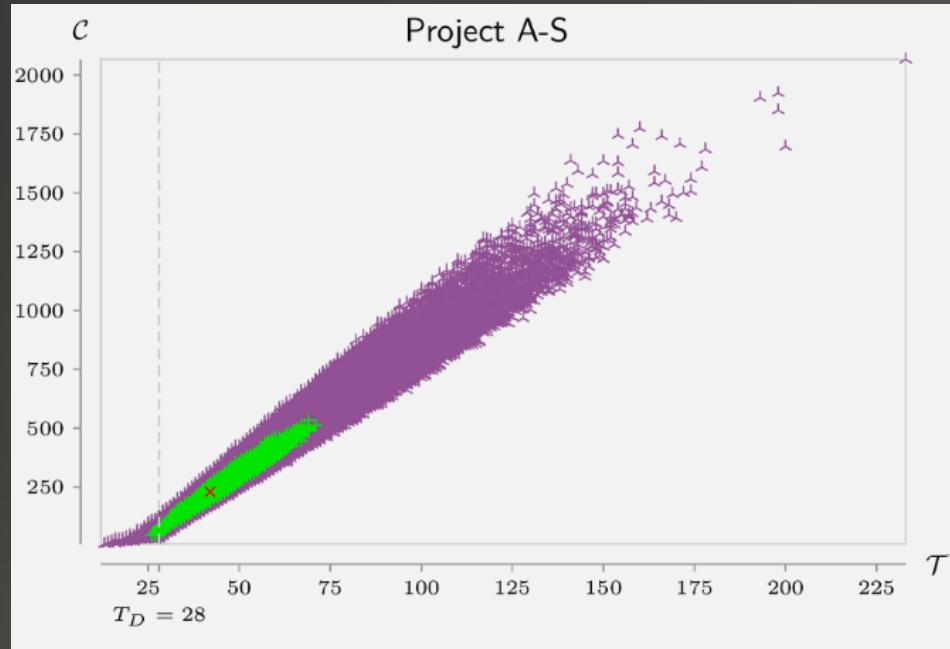


- DD & DL achieve both lesser cost and lesser timespan
- DD better at both cost and timespan than DL, in B-M

- DD & DL take much longer than LD & LL
- DD at B-M is abnormally greater

Discussion – Dispersion (A@DD)

Scatter Plots: Overall Distribution of the Obtained Results

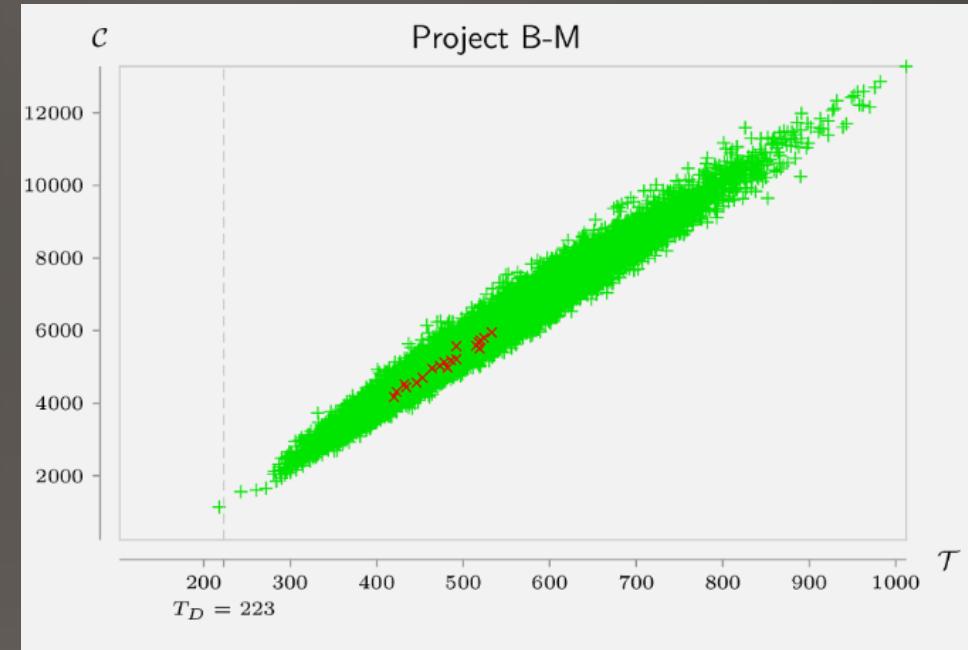
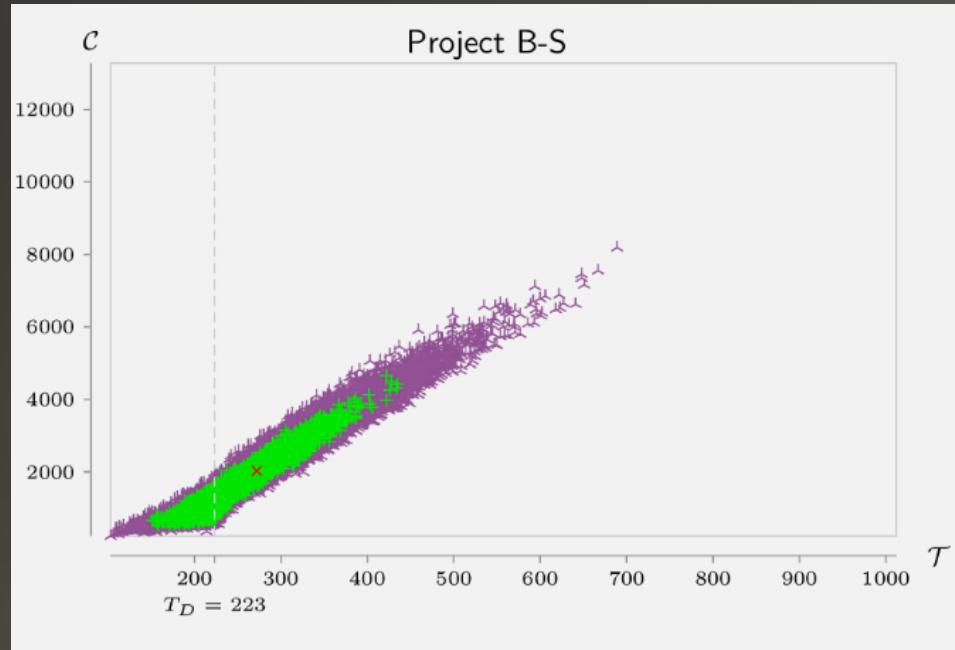


- Different behavior before and after T_D : bonus versus penalty
- More frequent results around T_D

- A-M with lesser timespan and cost: maximum availability is more permissive
- The cost amplitude, per each timespan value, is greater for A-M

Discussion – Dispersion (B@DD)

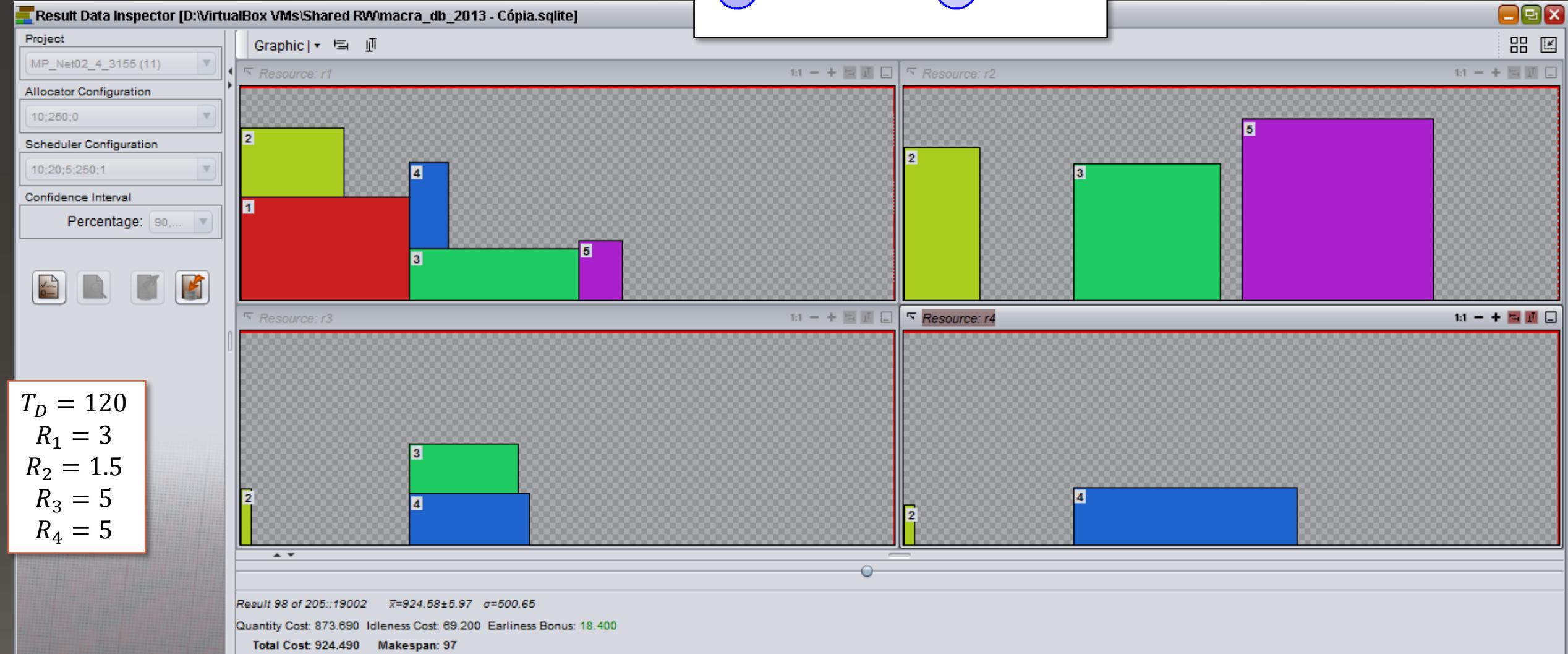
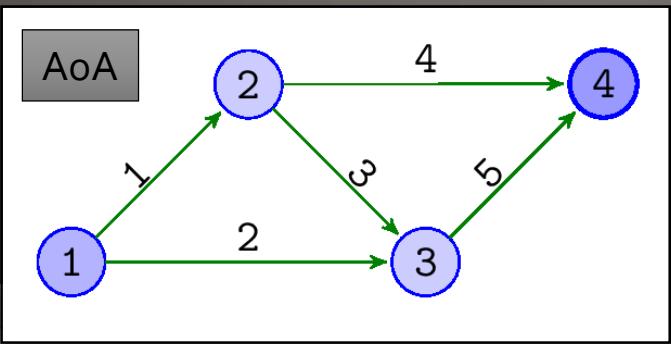
Scatter Plots: Overall Distribution of the Obtained Results



- B-S within A-S (and A-M) observations

- B-M results (almost) all above T_D .
- B-M not showing apparent convergence (multiple modal results)

Example



Conclusions

Sensibility

- EM algorithm configuration
- Maximum resource availability

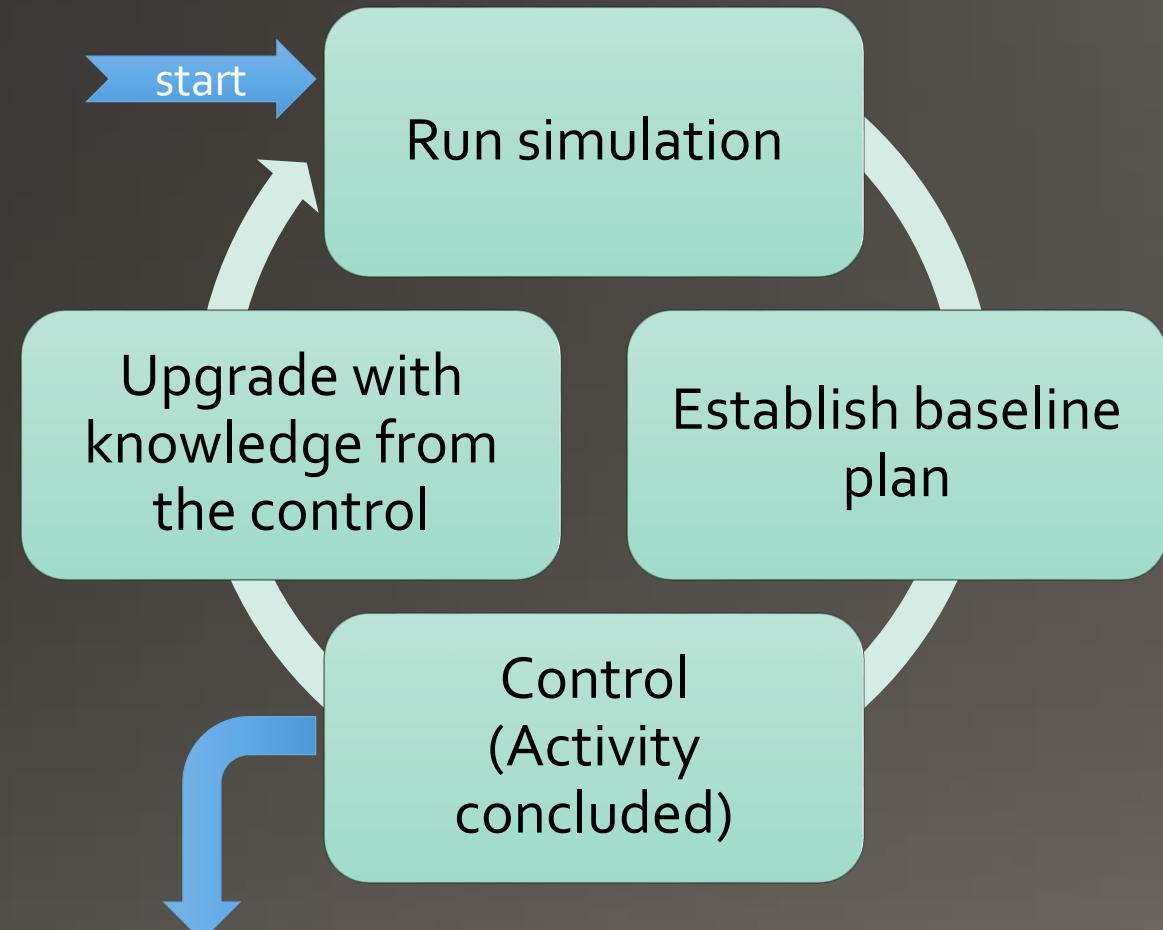
Multiple Resources

- Wider cost interval for each project duration (idleness cost)

Convergence

- Project duration tends towards due date
- Scarce results with both great cost and time
- Due date if overoptimistic may disrupt convergence

Future Research



Project Completed

Immediate caveats

- What to do if many activities finish at the same time (control)?
- The simulation rerunning must be kept swift



Your Questions!